

Decomposition of Multi-Player Games

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AI'09

Outline

- 1 Motivation
 - The Problem We Studied
 - General Idea We Used
- 2 Preliminaries
 - Game Description Language (GDL)
- 3 Subgame Detection
 - Basic Idea
- 4 Solving Decomposable Games
 - Motivation
 - Subgame Search
 - Global Game Search
- 5 Experimental Results and Conclusion
 - Experimental Results
 - Conclusion

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The Problem We Studied

Chess



Chess

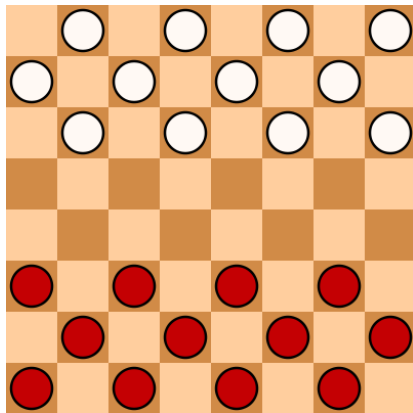
Deep Blue beats World Champion (1997)



AP / Adam Nadel, File

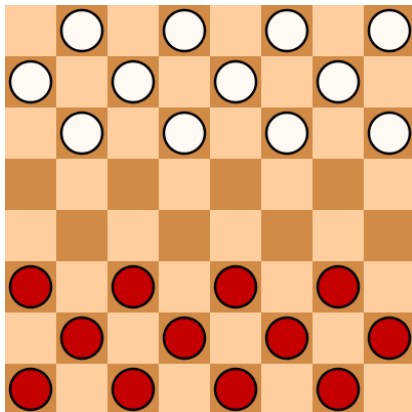
The Problem We Studied

Checker



Checker

Can Deep Blue play checkers?



General Game Playing

A General Game Player is a system that

- able to accept a formal description of **arbitrary** games
- able to use such descriptions to play the games **effectively**

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Constraints:

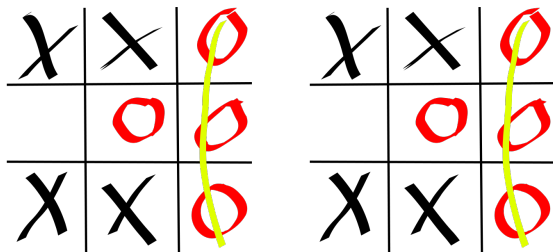
- **Time constraints** vs. **Very large games**

Observation:

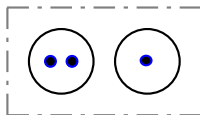
- Games contain **independent** parts (*subgames*)

Games Contain Subgames

Double-TicTacToe:



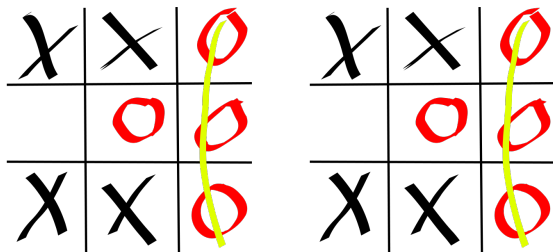
Nim:



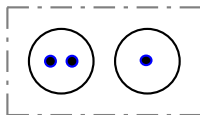
Games Contain Subgames

Improve game search by using their subgames?

Double-TicTacToe:



Nim:



Decomposition

- Widely recognized in AI Planning
- Adapted to General Game Playing
 - 1 How to **decompose**?
 - 2 How to **improve search** with decomposition?
- Previous Work
 - Single Player Games:
M. Günther, S. Schiffel, and M. Thielscher: *Factoring general games*. GIGA, 2009

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What is GDL

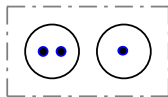
- Variant of Datalog (Prolog)
- Purely axiomatic (*no algebra and arithmetics*)
- Expressive power
 - 1 n -player ($n \geq 1$)
 - 2 deterministic
 - 3 perfect information

How to describe games in DGL

- Player: *role*(xplayer).
- State: set of terms (*fluents*), {cell(1,1,b),...}
 - initial state: *init*(cell(1,1,b)).
- Action: *legal*(Player,Action) \Leftarrow *true*(cell(1,1,b)),...
- Transition: *next*(F) \Leftarrow *does*(...),*true*(...),...
- Termination: *terminal* \Leftarrow line(x).
- Goal/Payoff: *goal*(xplayer, 100) \Leftarrow line(x).

Keywords: *role, init, legal, does, next, terminal, goal, and true.*

Game Nim in GDL



```

(role player1)
(role player2)

(init (heap a 1))
(init (heap b 2))
(init (control player1))

(<= (legal ?p (reduce ?x ?n))
    (true (control ?p))
    (true (heap ?x ?m))
    (smaller ?n ?m))

    (<= (next (heap ?x ?n))
        (does ?p (reduce ?x ?n)))
    ...
    (<= terminal
        (true (heap a 0))
        (true (heap b 0)))
    (<= (goal ?p 0)
        (true (control ?p)))
    ...

```

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Definitions

Definition

(Game). A **game** is a tuple $G = (F, A, I, R)$ where

- F is a set of fluents,
- A is a set of actions,
- I is the initial state, a set of ground instances of F ,
- R is a set of roles.

Definitions

Definition

(Subgame). A game $G = (F, A, I, R)$ is a **subgame** of $G' = (F', A', I', R')$ iff $F \subseteq F'$, $A \subseteq A'$, $I \subseteq I'$, $R \subseteq R'$, and F , A , I and R are not empty.

Definition

(Subgame Independence). Two subgames $G_s = (F_s, A_s, I_s, R_s)$ and $G_{s'} = (F_{s'}, A_{s'}, I_{s'}, R_{s'})$ of game G are **independent** each other iff $F_s \cap F_{s'} = \emptyset$ and $A_s \cap A_{s'} = \emptyset$.

Dependency Relations between **Fluents** and **Actions**

Potential Precondition (e.g.)

(\leq (**legal** ?p (reduce ?x ?n))
(**true** (heap ?x ?m))...)

(*heap ?x ?m*) is a
precondition of (*reduce ?x
?n*)

Potential Positive Effect (e.g.)

(\leq (**next** (heap ?x ?n))
(**does** ?p (reduce ?x ?n)))

(*reduce ?x ?n*) is a positive
effect of (*heap ?x ?m*)

Potential Negative Effect

F is a negative effect of M if F is **true now**, and F might be **false after** execution of M

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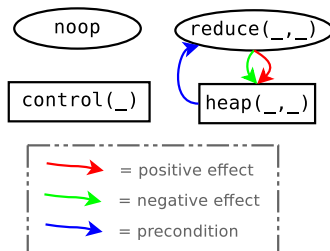
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Finding Independent Subgames

Subgames

connected components of fluents and actions

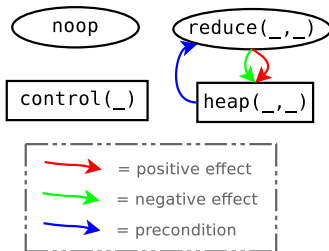


Finding Independent Subgames

Problem

subgames **share** fluent and action **names**

- obvious subgames (*heap a* and *heap b*) are still connected

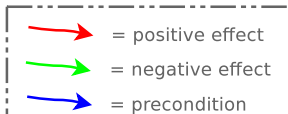
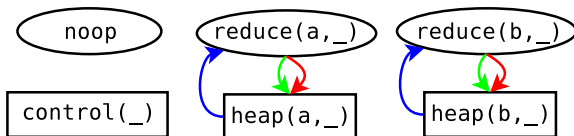


Finding Independent Subgames

Solution

argument instantiation

- *fluent*: argument's value does **NOT** change in the whole game
- *move*: refers to an **instantiated argument of a fluent**



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Decomposition Search

Main Idea

- 1 search subgames separately (*Subgame Search*)
- 2 build global plans with subgame plans (*Global Game Search*)

Problem

- *goal* and *terminal* conditions are **NOT** defined for subgames

Decomposition Search

Main Idea

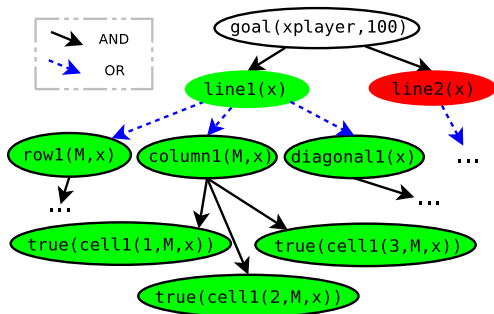
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- *goal* and *terminal* conditions are **NOT** defined for subgames

Local Concept (*goal and terminal rule decomposition*)

Local Concept detection example (*double-tictactoe*):
 (\leq (goal xplayer 100) (line1 x) (line2 x))

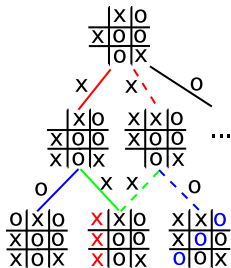


Local Concepts: $\text{line1}(x)$, $\text{line2}(x)$

Turn-Move Sequence

Turn-Move Sequence

a sequence of pairs (*Player, Action*) (a *path* in subgame tree) + a set of evaluations of **local concepts** in the subgame



4 turn-move sequences for *xplayer*:

$[(x, \text{mark}(3, 1)) \circ (o, \text{mark}(1, 1)), \text{Eval1}]$

$[(x, \text{mark}(3, 1)) \circ (x, \text{mark}(1, 1)), \text{Eval2}]$

$[(x, \text{mark}(1, 1)) \circ (x, \text{mark}(3, 1)), \text{Eval3}]$

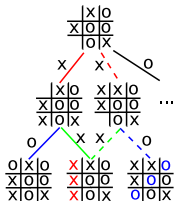
$[(x, \text{mark}(1, 1)) \circ (o, \text{mark}(3, 1)), \text{Eval4}]$

The Target of Subgame Search

Sequence Simplification

remove evaluation dominated sequences (*paths*)

- a seq is **evaluation dominated** if there is another **similar** seq with **better evaluations**
- a set of seqs S start with a move of player p is removed
 - if **all** $s \in S$ are dominated by other seqs start with other moves of p



$[(x, \text{mark}(3, 1)) \circ (o, \text{mark}(1, 1)), \text{Eval}1]$

$[(x, \text{mark}(3, 1)) \circ (x, \text{mark}(1, 1)), \text{Eval}2]$

The following two are dominated by the above:

$[(x, \text{mark}(1, 1)) \circ (x, \text{mark}(3, 1)), \text{Eval}3]$

$[(x, \text{mark}(1, 1)) \circ (o, \text{mark}(3, 1)), \text{Eval}4]$

Simple Example

Using normal search methods, for each state,

- choose legal moves from **turn-move sequences** returned from subgame search

Outline

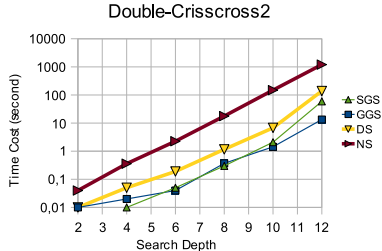
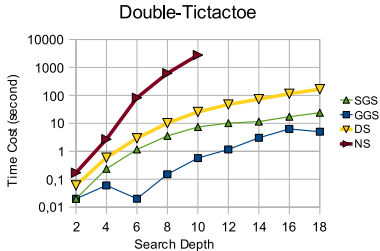
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Testing Results Comparison

time cost(second): for finding the first optimal strategy

DS: Decomposition Search; *NS*: Normal Search;

SGS: Subgame Search; *GGG*: Global Game Search



Done and ToDo

What we have done:

- 1 subgame detection
- 2 decomposition search (incl. a special version for impartial games)

Done and ToDo

What we have done:

- 1 subgame detection
- 2 decomposition search (incl. a special version for impartial games)

What can be improved:

- 1 more efficient subgame detection method
- 2 apply **pruning techniques** in decomposition search
- 3 use subgame plans **more efficiently** in global game search

Thank you for your attention!

For Further Reading I



John H. Conway

On Numbers and Games.

Academic Press, 1976.



Elwyn R. Berlekamp, John H. Conway, Richard K. Guy

Winning Ways 2nd Edition.

2001.



Martin Müller

Decomposition search: A combinatorial games approach to game tree search, with applications to solving Go endgames

1999.

For Further Reading II



M. Günther, S. Schiffel and M. Thielscher
Decomposition of Single Player Games
2007.



Eric Schkufza
Decomposition of Games for Efficient Reasoning
2008.

Time Complexity Comparison I

Impartial and Partial Games

Assume that a game G has n subgames, G_1, G_2, \dots, G_n with V_1, V_2, \dots, V_n states respectively,

- normal search: $O(V_1 * V_2 * \dots * V_n)$
- decomposition search: $O(V_1 + V_2 + \dots + V_n)$

Example

For double-tictactoe, the number of states is about $18!$ (including revisited states), while the state for each subgame is about $\prod_{n=1}^9 (2n)$ which is $\prod_{n=1}^9 (2n - 1)$ times smaller than $18!$

Time Complexity Comparison II

Parallel Games

Assume that a parallel game G has n subgames, G_1, G_2, \dots, G_n with V_1, V_2, \dots, V_n states respectively,

- normal search: $O(V_1 * V_2 * \dots * V_n)$
- decomposition search: $O(V_1 + V_2 + \dots + V_n)$

Serial Games

Assume that a serial game G has n subgames, for subgame i there are V_i states and T_i terminal states

- normal search:
 $O(V_1 + T_1 * V_2 + T_1 * T_2 * V_3 + \dots + T_1 * T_2 * \dots * T_{n-1} * V_n)$
- decomposition search: $O(V_1 + V_2 + \dots + V_n)$