

Fault Tolerant Mechanism Design for General Task Allocation

Dengji Zhao¹

Sarvapali Ramchurn¹

Nick Jennings²




¹University of Southampton, UK

²Imperial College London, UK

Task Allocation with Execution Uncertainty

Car repairing problem

Which garage should I visit to successfully fix my car with a minimal cost?

Garage	Cost/Suggestion	Rating (<i>Prob. of Success</i>)
	\$100	★★★☆☆ (0.5)
	\$150	★★★★☆ (0.8)
	\$200	★★★★★ (0.7)

The Key Literature

<i>Work</i>	<i>Domain</i>					
	<i>R</i>	<i>T</i>	<i>V</i>	<i>W</i>	<i>C</i>	Others
[Porter 08]	1	multi	comb.	multi	fixed	

- R. Porter et al. *Fault tolerant mechanism design*. AIJ 2008.
 - single task requester with multiple tasks (combinatorial valuation), multiple workers with fixed and additive costs

The Key Literature

Work	Domain					
	<i>R</i>	<i>T</i>	<i>V</i>	<i>W</i>	<i>C</i>	Others
[Porter 08]	1	multi	comb.	multi	fixed	
[Ramchurn 09]	multi	multi	comb.	multi	fixed	trust

- S. D. Ramchurn et al. *Trust-based mechanisms for robust and efficient task allocation in the presence of execution uncertainty*. JAIR 2009.
 - multiple task requesters/workers (combinatorial valuation/fixed-cost), multiple tasks (exchange), trust-based execution uncertainty

The Key Literature

Work	Domain					
	<i>R</i>	<i>T</i>	<i>V</i>	<i>W</i>	<i>C</i>	Others
[Porter 08]	1	multi	comb.	multi	fixed	
[Ramchurn 09]	multi	multi	comb.	multi	fixed	trust
[Stein 11]	1	1	time	multi	fixed	redundancy

- S. Stein et al. *Algorithms and mechanisms for procuring services with uncertain durations using redundancy*. AIJ 2011.
 - single task with completion deadline, multiple workers (uncertain execution time, fixed costs), allow allocation redundancy

The Key Literature

Work	Domain					
	<i>R</i>	<i>T</i>	<i>V</i>	<i>W</i>	<i>C</i>	Others
[Porter 08]	1	multi	comb.	multi	fixed	
[Ramchurn 09]	multi	multi	comb.	multi	fixed	trust
[Stein 11]	1	1	time	multi	fixed	redundancy
[Conitzer 14]	1	1	time	multi	p-fix	pree.-redu.

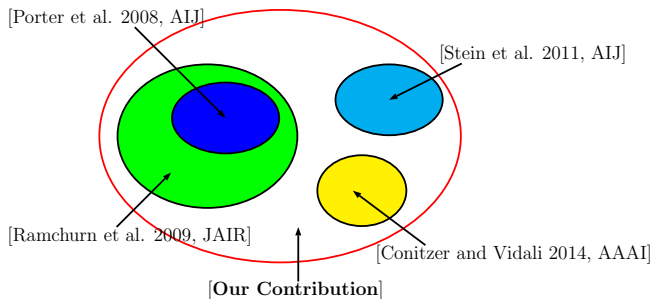
- V. Conitzer et al. *Mechanism design for scheduling with uncertain execution time*. AAAI 2014.
 - single task with completion deadline, uncertain execution time, allocation redundancy with preemption (partially fixed costs)

The Key Literature

Work	Domain					
	<i>R</i>	<i>T</i>	<i>V</i>	<i>W</i>	<i>C</i>	Others
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[Conitzer 14]	1	1	time	multi	p-fix	pree.-redu.

- Their common features:
 - efficient (*optimal in its range* [Nisan and Ronen 2007]) task allocation
 - pay according to the execution outcome (verification-based)

Our Contribution (Overview)



- **generalise** the task allocation domain
- **characterise** the applicability of the Vickrey-type mechanisms with verification (fault tolerant mechanisms)

Outline

- 1 Motivation
- 2 **Our Contribution**
 - What is Fault Tolerant Design?
 - Our Generalisation
- 3 Summary

A Single Task Allocation Problem

without Execution Uncertainty:

task (valuation)	costs
	\vdots
	v_1
	c_2
	v_1
$\tau_0 (v_0)$	c_1

- Vickrey outcome (efficient, truthful and individually rational):
 - allocate τ_0 to worker 1
 - pays worker 1 c_2
 - worker 1's utility is $c_2 - c_1$

A Single Task Allocation Problem

task	costs
	\vdots
	v_1
	c_2
	v_1
$\tau_0 (v_0)$	c_1

- Vickrey outcome:
 - allocate τ_0 to worker 1
 - pay worker 1 c_2
 - worker 1's utility is $c_2 - c_1$

task	costs (fixed)	prob.
	\vdots	\vdots
	v_1	\wedge_1
	c_2	p_2
	v_1	\wedge_1
$\tau_0 (v_0)$	c_1	p_1

- Vickrey outcome:
 - allocate τ_0 to worker 1
 - pay worker 1

$$v_0 \times p_1 - (v_0 \times p_2 - c_2) =$$

$$v_0 \times (p_1 - p_2) + c_2$$
 - worker 1's utility is

$$v_0 \times (p_1 - p_2) + c_2 - c_1$$

Fault Tolerant Mechanism Design

task	costs (fixed)	prob.
	\vdots	\vdots
	v_1	\wedge_1
	c_2	p_2
	v_1	\wedge_1
$\tau_0 (v_0)$	c_1	p_1

- Vickrey outcome:

- allocate τ_0 to worker 1

- pay worker 1

$$v_0 \times p_1 - (v_0 \times p_2 - c_2) =$$

$$v_0 \times (p_1 - p_2) + c_2$$

Vickrey with verification (*fault tolerant [Porter et al. 2008]*):

- allocate τ_0 to worker 1,
- **pay** worker 1 $v_0 \times (1 - p_2) + c_2$ if τ_0 is completed,
- **charge** him $v_0 \times p_2 - c_2$, otherwise.
- worker 1's expected payment is

$$p_1 \times (v_0 \times (1 - p_2) + c_2) - (1 - p_1) \times (v_0 \times p_2 - c_2) =$$

$$v_0 \times (p_1 - p_2) + c_2$$

The General Model

- n agents $N = \{1, \dots, n\}$.
- task allocation space T , each $\tau \in T$ is defined by $\tau = (\tau_i)_{i \in N}$, where τ_i is a set of tasks assigned to agent i .
- $p_i^T \in [0, 1]$ is the probability that i will successfully complete her tasks τ_i . $p_i = (p_i^T)_{T \in T}$ is i 's **probability of success (PoS)** profile.
- i 's valuation is defined by $v_i : T \times [0, 1]^N \rightarrow \mathbb{R}$. v_i considers **variable-costs, externalities, and task interdependences**.
- define agent i 's **type** by $\theta_i = (v_i, p_i)$.

The Post-Execution Verification (PEV) Mechanism

Given the agents' true type profile θ , their reports $\hat{\theta}$, and efficient allocation π^* , **PEV-based payment** x_i^{PEV} for each agent i is defined as:

$$x_i^{PEV}(\hat{\theta}) = \begin{cases} h_i(\hat{\theta}_{-i}) - V_{-i}^1(\hat{\theta}, \pi^*) & \text{if } i \text{ succeeded,} \\ h_i(\hat{\theta}_{-i}) - V_{-i}^0(\hat{\theta}, \pi^*) & \text{if } i \text{ failed.} \end{cases}$$

where

- $h_i(\hat{\theta}_{-i}) = \sum_{j \in N \setminus \{i\}} \hat{v}_j(\pi^*(\hat{\theta}_{-i}), (0, \hat{p}_{-i}^{\pi^*(\hat{\theta}_{-i})}))$
- $V_{-i}^1(\hat{\theta}, \pi^*) = \sum_{j \in N \setminus \{i\}} \hat{v}_j(\pi^*(\hat{\theta}), (1, \mathbf{p}_{-i}^{\pi^*(\hat{\theta})}))$,
- $V_{-i}^0(\hat{\theta}, \pi^*) = \sum_{j \in N \setminus \{i\}} \hat{v}_j(\pi^*(\hat{\theta}), (0, \mathbf{p}_{-i}^{\pi^*(\hat{\theta})}))$.

Conditions for PEV to be Ex-Post Truthful and IR

Theorem

Mechanism (π^*, x^{PEV}) is *ex-post truthful* iff for all $i \in N$, v_i is multilinear in probability of success (i.e., *risk-neutral*).

- *ex-post truthfulness* requires that reporting truthfully maximises an agent's expected utility, if everyone else also reports truthfully.

Theorem

Mechanism (π^*, x^{PEV}) is *individually rational* iff for all $i \in N$, for all $\tau \in T$, if $\tau_i = \emptyset$, then $v_i(\tau, p^\tau) \geq 0$ for any $p^\tau \in [0, 1]^N$.

Extension to Trust-Based Environments

Trust-based environments:

- each agent's probability of success p_i is not completely predictable by the agent alone but **aggregated from all agents' private opinions** (known as trust [Ramchurn et al. 2009, JAIR]).
- $p_i^\tau = f_i^\tau(p_{1,i}^\tau, \dots, p_{n,i}^\tau)$ where $p_{i,j}^\tau$ is the probability that i believes j will complete j 's tasks in τ .




Theorem

Mechanism (π^, x^{PEV}) is ex-post truthful in the trust-based environments iff for all $i \in N$,*

- v_i is multilinear in probability of success and
- aggregation f_i is multilinear.

In Summary




Post-Execution Verification Mechanism is “almost” universally applicable.

Garage	c_i	p_i
	\$100	0.5
	\$150	0.8
	\$200	0.7

- The social welfare of visiting each garage are:
 - $300 \times 0.5 - 100 = 50$
 - $300 \times 0.8 - 150 = 90$
 - $300 \times 0.7 - 200 = 10$
- The payments are:
 - pay the garage $300 - 50$ (if succeeded)
 - charge the garage 50 (otherwise)

In Summary

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Question

Possible/how to design truthful mechanisms for **non-risk-neutral** settings?